

Beyond Steering Vector: Flow-Based Activation Steering for Inference-Time Intervention

A general, zero-shot, state-of-the-art activation-steering method

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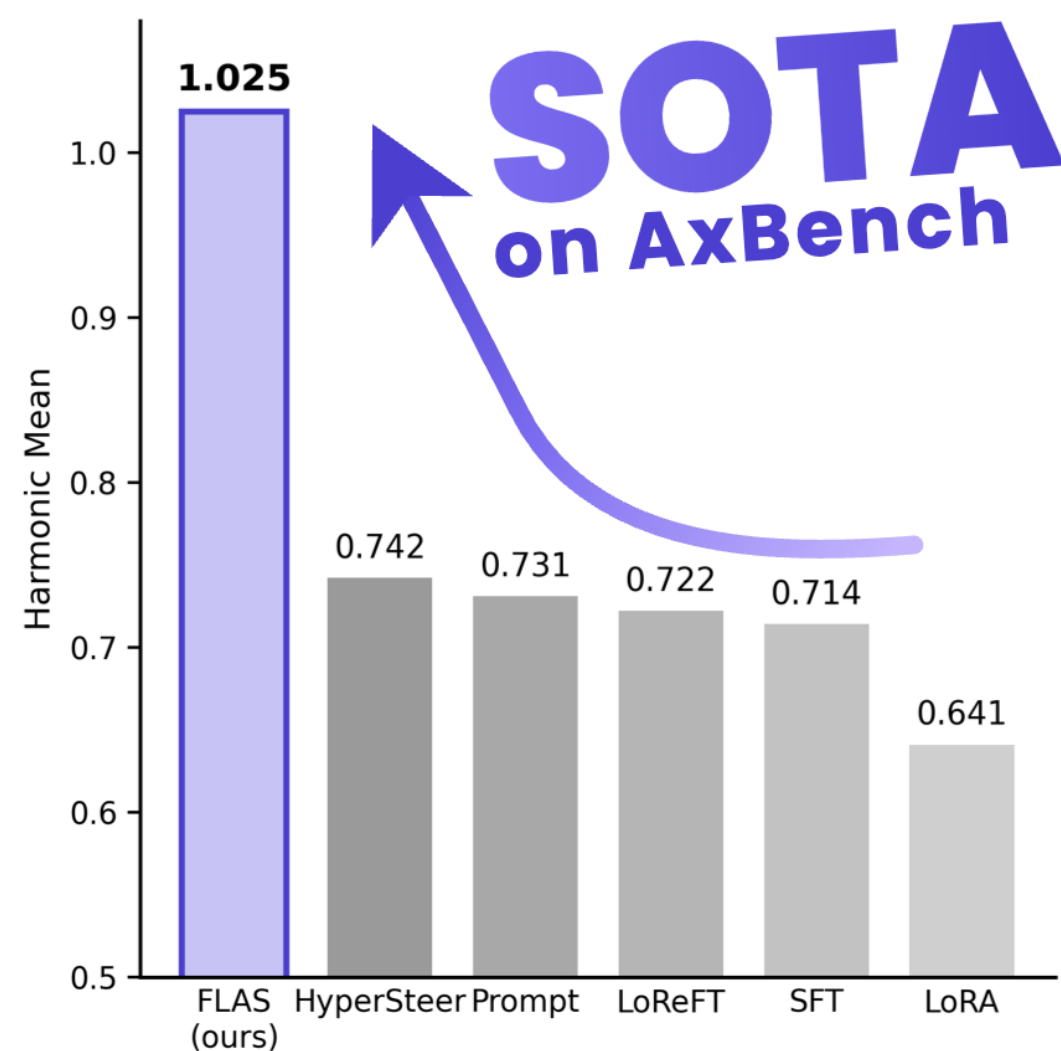
Website



HF Demo

RESULT · AXBENCH / CONCEPT16K

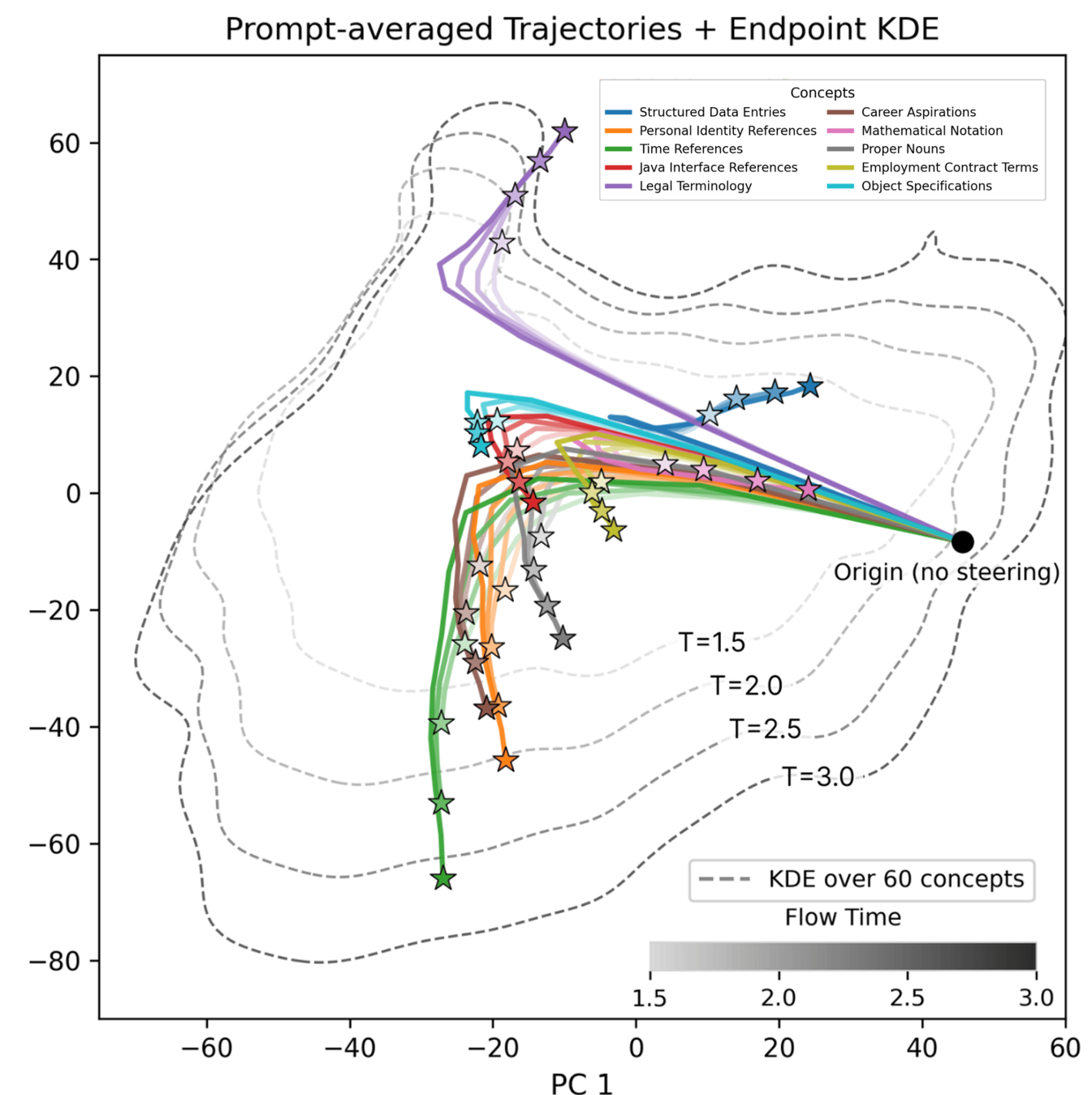
SOTA on AxBench



Method	Gemma-2-2B-IT		Gemma-2-9B-IT	
	Held-in	Held-out	Held-in	Held-out
Prompting	0.731	0.762	1.075	1.091
Fine-tuning				
LoReFT	0.722	—	0.777	—
SFT	0.714	—	—	—
LoRA	0.641	—	0.602	—
RePS	0.606	—	0.892	—
Activation Steering				
HyperSteer	0.742	0.608	1.091	0.934
ReFT-r1	0.509	—	0.630	—
AcT (All Layers)	0.187	—	0.161	—
DiffMean	0.178	—	0.322	—
SAE	0.151	—	0.191	—
AcT (Layer 20)	0.144	—	0.270	—
SAE-A	0.132	—	0.186	—
FLAS (ours)	1.025	1.015	1.185	1.113

ANALYSIS · FLOW TRAJECTORIES

Steering Space



1 Steering Lags Prompting

Activation steering edits hidden states with the LM **frozen**, yet on **AxBench** it is beaten by prompting: scalar strength trades concept incorporation against **instruction-following** and **fluency**.

Why? Prior methods assume *fixed, single-step, position-invariant* transforms, trained per concept.

3 First to Beat Prompting

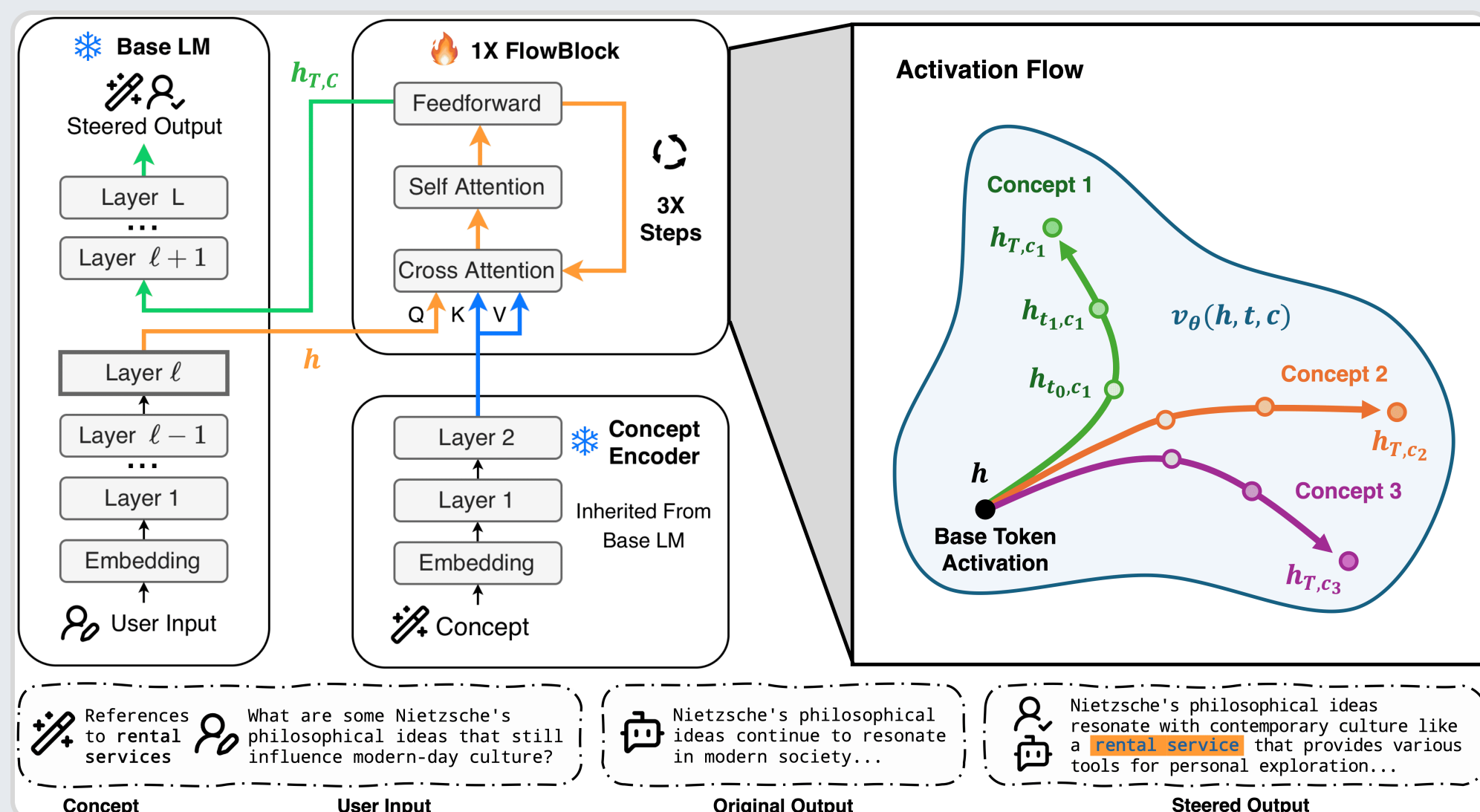
AxBench / Concept16k, fixed $T=2$, no tuning; full table in the headline chart above.

- Beats prompting held-out by **+0.253** (2B) / **+0.022** (9B) — first learned steerer to do so.
- Beats HyperSteer by **+0.407** / **+0.179** with **<1/26** the params, and **transfers** to Qwen3-4B (held-out **0.960**).

2 FLAS: Flow-Based Steering

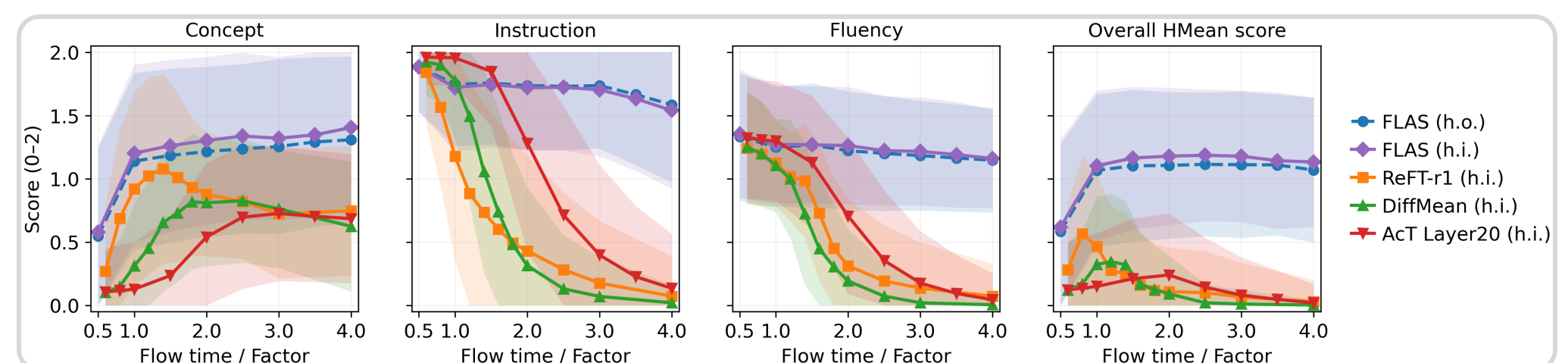
Learn a concept-conditioned **velocity field** $v_\theta(h, t, c)$ that transports h to a steered h' at frozen layer ℓ :

$$h' = \varphi_T(h) = h + \int_0^T v_\theta(\varphi_t(h), t, c) dt$$



A single FlowBlock (97.6M/255M trained params) cross-attends to a frozen encoder $\phi(c)$; **adaptive**, **multi-step** & **per-token**, positive-only training.

4 Robust Strength & Scaling



Strength trade-off (9B-IT). Baselines **collapse** at higher strength; FLAS keeps raising concept score while holding instruction & fluency, stable over $T \in [0.5, 4.0]$.

- **Scaling.** Held-out HMean rises **monotonically** with training concepts (9 → 16k).
- **Ablations.** Cross-attention is essential (0.109 without); $N=1$ still beats prompting.

5 The Geometry of Flow Steering

- **Curved** — trajectories bend; not straight lines.
- **Multi-step** — late Euler steps align (cosine >0.7), early steps differ (<0.25).
- **Per-token** — mean pairwise cosine only **0.294** (uniform = 1.0), so steering must be **nonlinear & position-sensitive**.